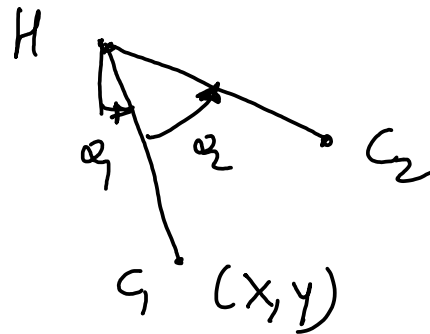


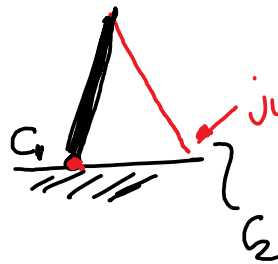
Equations for footstrike

$$M \ddot{z} = B(\theta, \dot{\theta}) + J_{C_1}^T F_{C_1} + J_{C_2}^T F_{C_2}$$



$$\theta = \{\theta_1, \theta_2\}$$

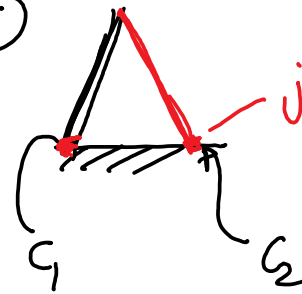
t^-
(-)



just before collision

$$v_{C_1}^- = 0$$

t^+
(+)



just after collision

$$v_{C_2}^+ = 0$$

- denotes before collision

+ denotes after collision

$$\int_{t^-}^{t^+} M \ddot{z} dt = \int_{t^-}^{t^+} B(\theta, \dot{\theta}) dt + \int_{t^-}^{t^+} J_{C_1}^T (F_{C_1}) dt + \int_{t^-}^{t^+} J_{C_2}^T (F_{C_2}) dt$$

$\int_{t^-}^{t^+} B(\theta, \dot{\theta}) dt$ → Coriolis, centripetal
 $\int_{t^-}^{t^+} J_{C_1}^T (F_{C_1}) dt$ → impulse
 $\int_{t^-}^{t^+} J_{C_2}^T (F_{C_2}) dt$ → impulse P_{C_2}

$$M (\dot{z}^+ - \dot{z}^-) = J_{C_2}^T P_{C_2}$$

\dot{z}^+ at t^+
 \dot{z}^- at t^-

$$V_{C_2}^+ = J_{C_2} \dot{z}^+ = 0 \quad - (2)$$

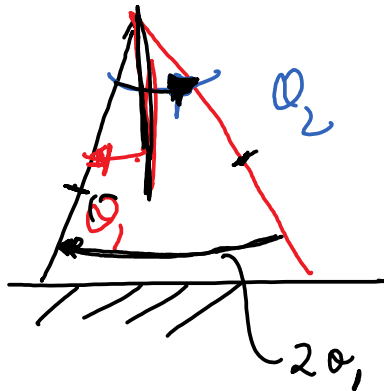
$$M (\dot{z}^+ - \dot{z}^-) = J_{C_2}^T P_{C_2} \quad - (1) \text{ (from previous page)}$$

$$\underline{M} \dot{z}^+ - J_{C_2}^T P_{C_2} = M \dot{z}^- \quad - (1a)$$

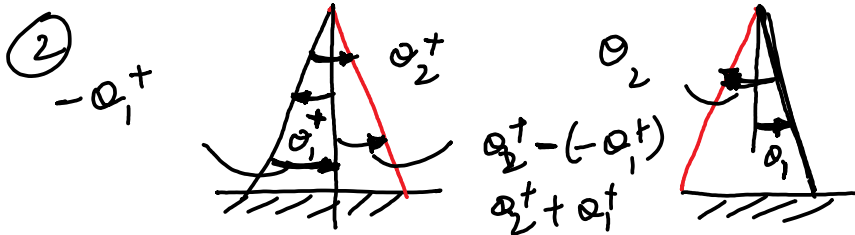
From (1a) & (2)

$$\begin{bmatrix} \underline{M} & -J_{C_2}^T \\ J_{C_2} & 0 \end{bmatrix} \begin{bmatrix} \dot{z}^+ \\ P_{C_2} \end{bmatrix} = \begin{bmatrix} M \dot{z}^- \\ 0 \end{bmatrix} \quad - (1b)$$

① Detect collision



$$\theta_2 = -2\theta_1 \Rightarrow \boxed{\theta_2 + 2\theta_1 = 0}$$



Just after footstrike swap.

$$\boxed{\theta_2 = -\theta_2^+ ; \quad \theta_1 = \theta_1^+ + \theta_1^+}$$