

A1 with GUI:

1. Clone my MuJoCo instance and copy over my a1_main.c (MujocoInstance/sample/a1_trotting_arm/a1_main.c) to yours
git clone <https://github.com/cd-1578/MujocoInstance.git>
2. There will probably be issues with including some of the headers since they were located in different places on my computer. Reference the original version of a1_trotting9 you sent me and adjust the headers names and use of <> or "" to include. None of the headers should be deleted.
3. Clone my GUI. All that is needed is the "Exec" folder which contains the RoboUI binary for Windows.
git clone <https://github.com/cd-1578/RoboGUI.git>
4. Running the GUI with the robot controller
 - a. Since the a1_main.c has the server code for the socket, it has to be launched first else the GUI will not be able to connect.