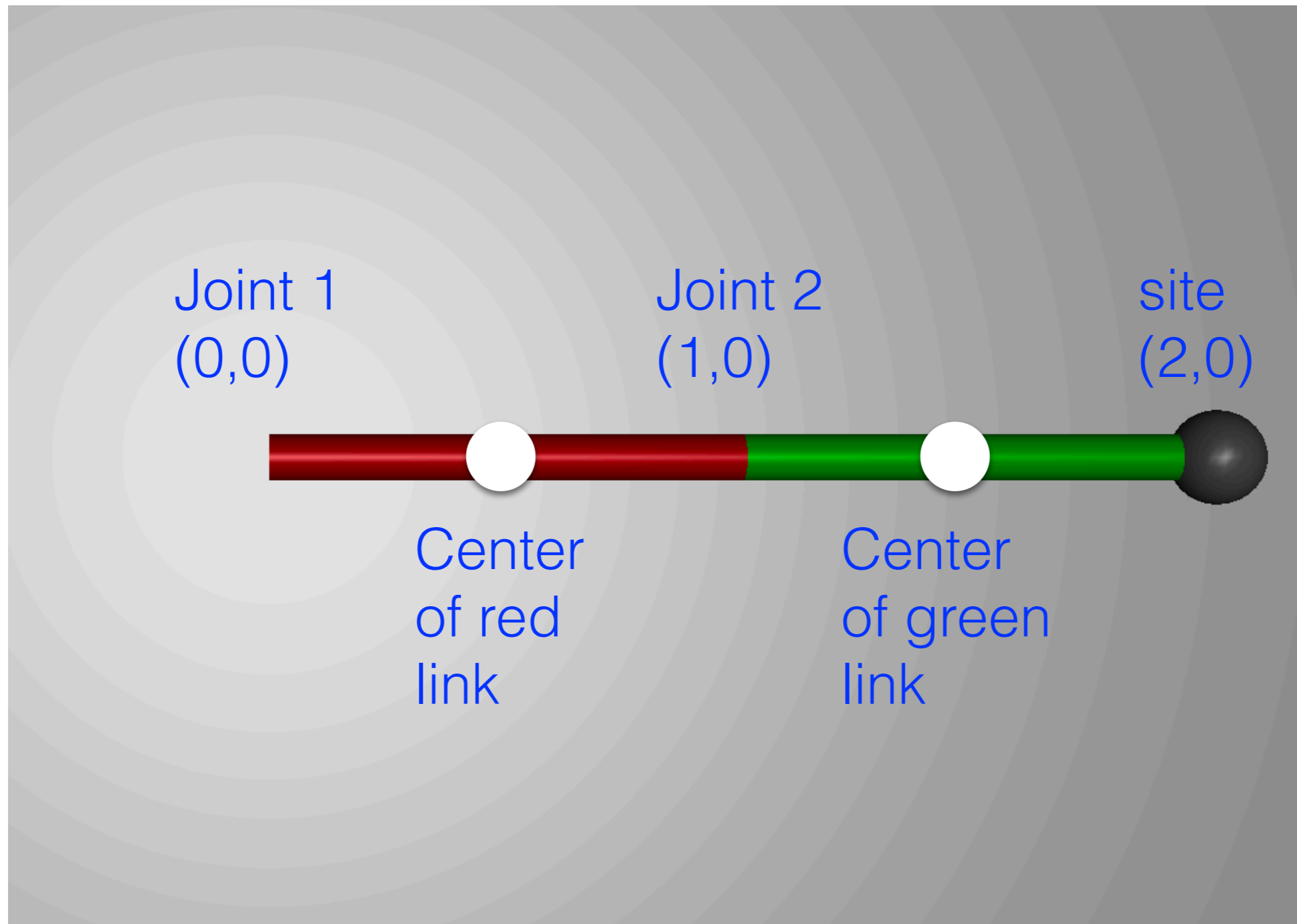
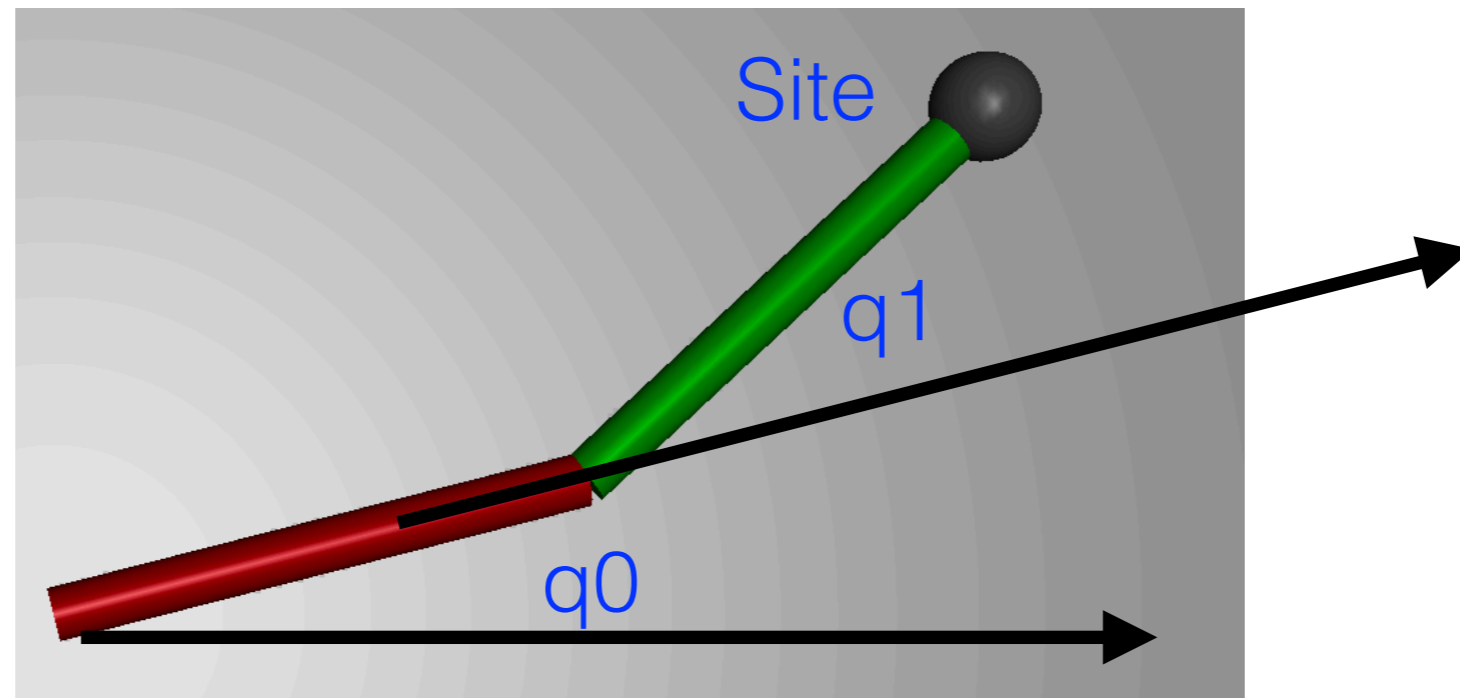


Planar, 2-link manipulator (model)



Planar, 2-link manipulator (kinematics)



```
data.qpos[0] = q0; data.qpos[1] = q1 #set position
```

```
mj_forward(model,data) #forward kinematics
```

```
data.site_xpos[0] #get site position
```